

IE170: Algorithms in Systems Engineering: Lecture 21

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Taking Stock

Last Time

- Shortest Paths
- TSP in Lab

This Time

- Shortest Paths

Shortest Paths—Definitions

- For the next few lectures, we will have a **directed** graph $G = (V, E)$, and a weight function $w : E \rightarrow \mathbb{R}^{|E|}$.
- We are interested in finding the shortest-path weights from u to v , which we will denote $\delta(u, v)$.
- $\delta(u, v) = \infty$ if there is no path from u to v in G
- (Single Source) shortest-path algorithms produce a label: $d[v] = \delta(s, v)$.
- Initially $d[v] = \infty$, reduces as the algorithm goes, so always $d[v] \geq \delta(s, v)$
- Also produce labels $\pi[v]$, predecessor of v on a shortest path from s .



Initializing and Relaxing

INIT-SINGLE-SOURCE(V, s)

```

1 for each  $v$  in  $V$ 
2   do  $d[v] \leftarrow \infty$ 
3      $\pi[v] \leftarrow \text{NIL}$ 
4    $d[s] \leftarrow 0$ 

```

RELAX(u, v, w)

```

1 if  $d[v] > d[u] + w_{uv}$ 
2   then  $d[v] \leftarrow d[u] + w_{uv}$ 
3      $\pi[v] \leftarrow u$ 

```

Lemmas

Lemma

Any subpath of a shortest path is a shortest path

Lemma

Shortest paths can't contain cycles

Path Relaxation Property

Let $P = \{v_0, v_1, \dots, v_k\}$ be a shortest path from $s = v_0$ to v_k . If the edges (v_0, v_1) , (v_1, v_2) , (v_{k-1}, v_k) are relaxed **in that order**, (there can be other relaxations in-between), then $d[v_k] = \delta(s, v_k)$



Bellman-Ford Algorithm

- Works with Negative-Weight Edges
- Returns **true** if there are no negative-weight cycles reachable from s , **false** otherwise

BELLMAN-FORD(V, E, w, s)

```

1 INIT-SINGLE-SOURCE( $V, s$ )
2 for  $i \leftarrow 1$  to  $|V| - 1$ 
3   do for each  $(u, v)$  in  $E$ 
4     do RELAX( $u, v, w$ )
5 for each  $(u, v)$  in  $E$ 
6   do if  $d[v] > d[u] + w_{uv}$ 
7     then return False
8   return True

```



Single Source Shortest Path on a DAG

DAG-SHORTEST-PATHS(V, E, s, w)

```

1 INIT-SINGLE-SOURCE( $V, s$ )
2 topologically sort the vertices (HOW)
3 for each  $u$  in topologically sorted  $V$ 
4   do for each  $v \in Adj[u]$ 
5     do RELAX( $u, v, w$ )

```



SSSP-DAG Analysis and Correctness

- Correctness
 - Since vertices are processed in topologically sorted order, edges of **any** path are relaxed in order of appearance on the path
 - Thus, edges on any shortest path are relaxed in order
 - Thus, by the path-relaxation lemma, the algorithm is correct
- Analysis
 - Can You Do It!?!?!?



Dijkstra's Algorithm

- Works only if the graph has no negative-weight edges
- This is essentially a weighted-version of BFS
 - Instead of a FIFO Queue (like you used for BFS in the lab), use a priority queue
 - Keys (in PQ) are the shortest-path weight estimates ($d[v]$)
- In Dijkstra's Algorithm, we have two sets of vertices
 - S : Vertices whose final shortest path weights are determined
 - Q : Priority queue: $V \setminus S$



Dijkstra's Algorithm

```

DIJKSTRA( $V, E, w, s$ )
1  INIT-SINGLE-SOURCE( $V, s$ )
2   $S \leftarrow \emptyset$ 
3   $Q \leftarrow V$ 
4  while  $Q \neq \emptyset$ 
5  do  $u \leftarrow$  EXTRACT-MIN( $Q$ )
6      $S \leftarrow S \cup \{u\}$ 
7     for each  $v \in Adj[u]$ 
8     do RELAX( $u, v, w$ )
  
```



Dijkstra's Algorithm

- **Note:** Looks a lot like Prim's algorithm, but computing $d[v]$, and using the shortest path weights as keys
- Dijkstra's Algorithm is greedy, since it always chooses the "lightest" vertex in $V \setminus S$ to add to S



Dijkstra Analysis

- Analysis: Like Prim's Algorithm, depends on the time it takes to perform priority queue operations.
- Suppose we use a binary heap.
 - EXTRACT-MIN: Called $O(|V|)$ times
 - RELAX: Called $O(|E|)$ times
 - How long does each of these operations take?
- Dijkstra's Algorithm Runs in $O(E \lg V)$, with a binary heap implementation.
- Better Heap implementations get it down to $O(V \lg V + E)$.
- Our "List/Container" implementation took $O(V^2)$



Dijkstra Correctness.

Loop Invariant

- At the start of each iteration of the **while** loop
 $\delta(s, v) = d[v] \quad \forall v \in S$
- **Initially:** $S = \emptyset$, so this is trivially true
- **At end:** $S = V$, so we have the shortest path weights
- **Maintenance:** Must show that $d[u] = \delta(s, u)$ when u is added to S

We'll Give Proof (If Time)

