

# IE418: Integer Programming

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IE418 Integer Programming

Review  
Combinatorial Optimization Problems  
Special Ordered Sets  
“Algorithmic” Modeling

## Review

- Name two reasons why anyone would want to “program with integers”?
- What is the knapsack problem?
- (MIP):  $\max\{c^T x + h^T y \mid Ax + Gy \leq b, x \in \mathbb{Z}_+^n, y \in \mathbb{R}_+^p\}$ 
  - What is Mixed 0-1 Programming?
  - What is Pure Integer Programming
  - What is Binary Programming?
  - What is 0-1 Programming?
- What is  $\mathbb{Q}_+^n$ ?
- What is my son’s name?



## Outline

- Combinatorial Optimization Problems
  - Set {Packing, Covering, Partitioning}
  - TSP
- Special Ordered Sets
  - Models of Choice—"Pick one!"
  - Piecewise Linear Functions
- Algorithmic Modeling
  - The Bag of Tricks
  - A couple examples



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Set {Pack,Cover,Partition}ing  
Traveling Salesman

## Selecting from a Set

- We can use constraints of the form  $\sum_{j \in T} x_j \geq 1$  to represent that **at least one** item should be chosen from a set  $T$ .
  - Similarly, we can also model that **at most one** or **exactly one** item should be chosen.
- **Example**: Set covering problem
- If  $A$  in a 0-1 matrix, then a set covering problem is any problem of the form

$$\begin{aligned} \min \quad & c^T x \\ \text{s.t.} \quad & Ax \geq e^1 \\ & x_j \in \{0, 1\} \quad \forall j \end{aligned}$$

- **Set Packing**:  $Ax \leq e$
- **Set Partitioning**:  $Ax = e$

<sup>1</sup>It is common to denote the vector of 1's as  $e$

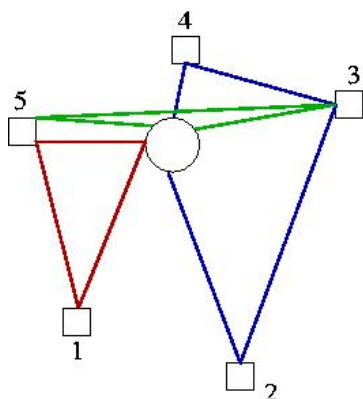


# COP—Set{Cover, Pack, Partition}ing

- A **combinatorial optimization problem**  $CP = (N, \mathcal{F})$  consists of
  - A finite **ground set**  $N$ ,
  - A set  $\mathcal{F} \subseteq 2^N$  of **feasible solutions**, and
  - A **cost function**  $c$
- Each **row** of  $A$  represents an item from  $N$
- Each **column**  $A_j$  represents a subset  $N_j \in \mathcal{F}$  of the items.
- Each **variable**  $x_j$  represents selecting subset  $N_j$ .
- The **constraints** (for covering and partitioning) say that  $\cup_{\{j|x_j=1\}} N_j = N$ .
- In other words, each item must appear in **at least**, (or **exactly one**) selected subset.



## Vehicle Routing



	$x_1$	$x_2$	$x_3$	...	
Customer 1 :	1	0	0	⋮	= 1
Customer 2 :	0	1	0	⋮	= 1
Customer 3 :	0	1	1	⋮	= 1
Customer 4 :	0	1	0	⋮	= 1
Customer 5 :	1	0	1	⋮	= 1

- This is a **very** flexible modeling trick
- You can list **all feasible routes**, allowing you to handle "weird" constraints like time windows, strange precedence rules, nonlinear cost functions, etc.



# The Farmer's Daughter

- This is *The Most Famous Problem in Combinatorial Optimization!*
- A traveling salesman must visit all his cities at minimum cost.
- Given directed (complete) graph with node set  $N$ .  
 $(G = (N, N \times N))$
- Given costs  $c_{ij}$  of traveling from city  $i$  to city  $j$
- Find a minimum cost **Hamiltonian Cycle** in  $G$
- **Variables:**  $x_{ij} = 1$  if and only if salesman goes from city  $i$  to city  $j$



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## TSP (cont.)

$$\min \sum_{i \in N} \sum_{j \in N} c_{ij} x_{ij}$$

$$\sum_{i \in N} x_{ij} = 1 \quad \forall j \in N \quad \text{Enter Each City}$$

$$\sum_{j \in N} x_{ij} = 1 \quad \forall i \in N \quad \text{Leave Each City}$$

$$x_{ij} \in \{0, 1\} \quad \forall i \in N, \forall j \in N$$

Subtour elimination constraint:

("No Beaming")

$$\sum_{i \in S} \sum_{j \notin S} x_{ij} \geq 1 \quad \forall S \subseteq N, 2 \leq |S| \leq |N| - 2$$

Alternatively:

("No Beaming")

$$\sum_{i \in S} \sum_{j \in S} x_{ij} \leq |S| - 1 \quad \forall S \subseteq N, 2 \leq |S| \leq |N| - 2$$



## TSP Trivia Time!

### What is This Number?

101851798816724304313422284420468908052573419683296  
8125318070224677190649881668353091698688.

- Is this...
  - a) The number of times an undergraduate student asked me where room 355 was this week?
  - b) The number of subatomic particles in the universe?
  - c) The number of subtour elimination constraints when  $|N| = 299$ .
  - d) All of the above?
  - e) None of the above?



## Answer Time

- The answer is (e). (a)–(c) are all too small (as far as I know :-). (It is (c), for  $|N| = 300$ ).
- “Exponential” is **really** big.
- Yet people have solved TSP’s with  $|N| > 16,000!$
- You will learn how to solve these problems too!
- The “trick” is to only add the subset of constraints that are necessary to prove optimality.
  - This is a trick known as **branch-and-cut**, and you will learn lots about branch-and-cut in this course.



## Modeling a Restricted Set of Values

- We may want variable  $x$  to only take on values in the set  $\{a_1, \dots, a_m\}$ .
- We introduce  $m$  binary variables  $y_j, j = 1, \dots, m$  and the constraints

$$x = \sum_{j=1}^m a_j y_j,$$

$$\sum_{j=1}^m y_j = 1,$$

$$y_j \in \{0, 1\}$$

- The set of variables  $\{y_1, y_2, \dots, y_m\}$  is called a **special ordered set** (SOS) of variables.



## Example—Building a warehouse

- Suppose we are modeling a facility location problem in which we must decide on the size of a warehouse to build.
- The choices of sizes and their associated cost are shown below:

Size	Cost
10	100
20	180
40	320
60	450
80	600

Warehouse sizes and costs



## Warehouse Modeling

- Using binary decision variables  $x_1, x_2, \dots, x_5$ , we can model the cost of building the warehouse as

$$\text{COST} \equiv 100x_1 + 180x_2 + 320x_3 + 450x_4 + 600x_5.$$

- The warehouse will have size

$$\text{SIZE} \equiv 10x_1 + 20x_2 + 40x_3 + 60x_4 + 80x_5,$$

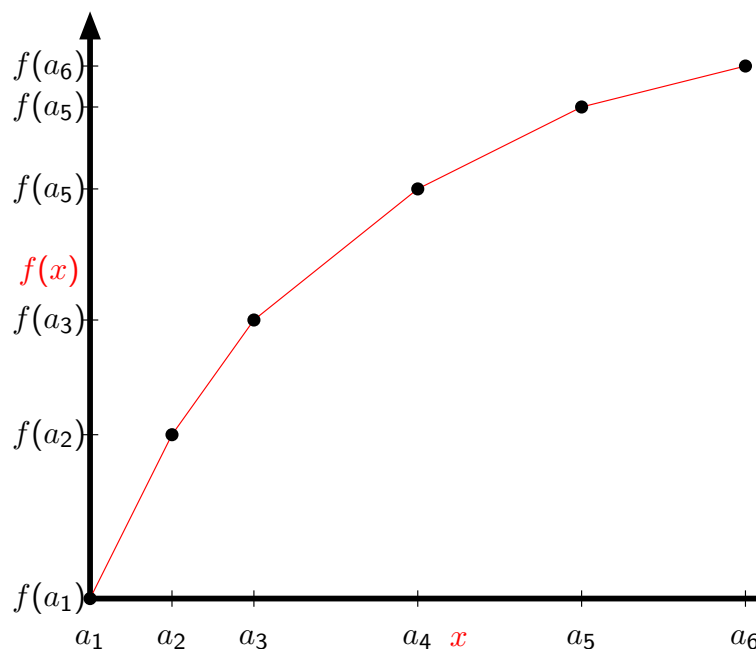
- and we have the SOS constraint

$$x_1 + x_2 + x_3 + x_4 + x_5 = 1.$$



## Piecewise Linear Cost Functions

- We can use binary variables to model arbitrary piecewise linear functions.
- The function is specified by ordered pairs  $(a_i, f(a_i))$
- We have a binary variable  $y_i$ , which indicates whether  $a_i \leq x \leq a_{i+1}$ .



## Minimizing Piecewise Linear Cost Functions

- To evaluate the function, we will take linear combinations  $\sum_{i=1}^k \lambda_i f(a_i)$  of the given functions values.
- This only works if the only two nonzero  $\lambda_i$ 's are the ones corresponding to the endpoints of the interval in which  $x$  lies.

$$\min \sum_{i=1}^k \lambda_i f(a_i)$$

$$\begin{aligned} \text{s.t. } \sum_{i=1}^k \lambda_i &= 1, \\ \lambda_1 &\leq y_1, \\ \lambda_i &\leq y_{i-1} + y_i, \quad i = 2, \dots, k-1, \\ \lambda_k &\leq y_{k-1}, \\ \sum_{i=1}^{k-1} y_i &= 1, \\ \lambda_i &\geq 0, \\ y_i &\in \{0, 1\}. \end{aligned}$$

### The Key Idea!

If  $y_j = 1$ , then  $\lambda_i = 0, \forall i \neq j, j+1$ .



## SOS2

- A "better" formulation involves the use of **special ordered sets of type 2**

### SOS2

A set of variables of which at most two can be positive. If two are positive, they must be adjacent in the set.

$$\min \sum_{i=1}^k \lambda_i f(a_i)$$

$$\begin{aligned} \text{s.t. } \sum_{i=1}^k \lambda_i &= 1 \\ \lambda_i &\geq 0 \end{aligned}$$

$\{\lambda_1, \lambda_2, \dots, \lambda_k\}$  SOS2

- The adjacency conditions of SOS2 are enforced by the solution algorithm
- (All) commercial solvers allow you to specify SOS2





## Modeling Disjunctive Constraints

- We are given two constraints  $a^T x \geq b$  and  $c^T x \geq d$  with nonnegative coefficients.
- Instead of insisting both constraints be satisfied, we want **at least one** of the two constraints to be satisfied.
- To model this, we define a **binary variable**  $y$  and impose

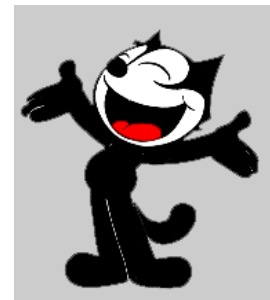
$$\begin{aligned} a^T x &\geq yb, \\ c^T x &\geq (1 - y)d, \\ y &\in \{0, 1\}. \end{aligned}$$

- More generally, we can impose that at least  $k$  out of  $m$  constraints be satisfied with

$$\begin{aligned} (a'_i)^T x &\geq b_i y_i, & i \in \{1, 2, \dots, m\} \\ \sum_{i=1}^m y_i &\geq k, \\ y_i &\in \{0, 1\} \end{aligned}$$



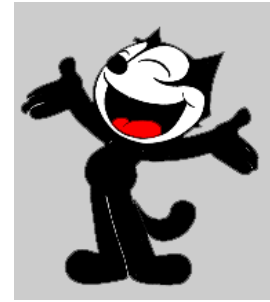
## The Bag of Tricks



- There are **lots** of things you can model with binary variables:

- Indicator variables (Positivity of variables)
  - Limiting the Number of Positive Variables
  - "Fixed Charge" problems
  - Minimum production level
- Indicator variables (Validity of constraints)
  - Either-or
  - If-then
  - $k$  out of  $n$





## The Bag of Tricks

- Special Ordered Sets
- Nonconvex regions
- Economies of Scale
- Discrete Capacity Extensions
- Maximax or Minimin

- The problem is that sometimes to see the modeling "trick" is difficult. For example...
- Use a 0-1 variable  $\delta$  to indicate whether *or not* the constraint  $2x_1 + 3x_2 \leq 1$  is satisfied.
  - $x_1, x_2$  are nonnegative continuous variables that are  $\leq 1$
- $\delta = 1 \Leftrightarrow 2x_1 + 3x_2 \leq 1$



## The Slide of Tricks. Indicator Variables...

- $\delta = 1 \Rightarrow \sum_{j \in N} a_j x_j \leq b$ 
  - $\sum_{j \in N} a_j x_j + M\delta \leq M + b$
- $\sum_{j \in N} a_j x_j \leq b \Rightarrow \delta = 1$ 
  - $\sum_{j \in N} a_j x_j - (m - \epsilon)\delta \geq b + \epsilon$
- $\delta = 1 \Rightarrow \sum_{j \in N} a_j x_j \geq b$ 
  - $\sum_{j \in N} a_j x_j + m\delta \geq m + b$
- $\sum_{j \in N} a_j x_j \geq b \Rightarrow \delta = 1$ 
  - $\sum_{j \in N} a_j x_j - (M + \epsilon)\delta \leq b - \epsilon$

### Definitions

- $\delta$ : Indicator variable ( $\delta \in \{0, 1\}$ ).
- $M$ : Upper bound on  $\sum_{j \in N} a_j x_j - b$
- $m$ : Lower bound on  $\sum_{j \in N} a_j x_j - b$
- $\epsilon$ : Small tolerance beyond which we regard the constraint as haven been broken.
  - If  $a_j \in \mathbb{Z}$ ,  $x_j \in \mathbb{Z}$ , then we can take  $\epsilon = 1$ .



## Modeling Trick #1

- Indicating Constraint (Non)violation
- Suppose we wish to indicate whether or not an inequality  $\sum_{j \in N} a_j x_j \leq b$  holds by means of an indicator variable  $\delta$ .

### Implication We Wish to Model

$$\delta = 1 \Rightarrow \sum_{j \in N} a_j x_j \leq b$$

- This can be represented by the constraint
  - $\sum_{j \in N} a_j x_j + M\delta \leq M + b$



## Trick #1... The Logic

$$\delta = 1 \Rightarrow \sum_{j \in N} a_j x_j \leq b \Leftrightarrow \sum_{j \in N} a_j x_j + M\delta \leq M + b$$

- (Thinking)...
  - $\delta = 1 \Rightarrow \sum_{j \in N} a_j x_j - b \leq 0$
  - $1 - \delta = 0 \Rightarrow \sum_{j \in N} a_j x_j - b \leq 0$
  - $\sum_{j \in N} a_j x_j - b \leq M(1 - \delta)$
- Does it work?
  - $\delta = 0 \Rightarrow \sum_{j \in N} a_j x_j - b \leq M$ 
    - (true by definition of  $M$ )
  - $\delta = 1 \Rightarrow \sum_{j \in N} a_j x_j - b \leq 0$



## Modeling Trick #2

$$\sum_{j \in N} a_j x_j \leq b \Rightarrow \delta = 1$$

- $\delta = 0 \Rightarrow \sum_{j \in N} a_j x_j \not\leq b$
- $\delta = 0 \Rightarrow \sum_{j \in N} a_j x_j > b$
- $\delta = 0 \Rightarrow \sum_{j \in N} a_j x_j \geq b + \epsilon$ 
  - If  $a_j, x_j$  are integer, we can choose  $\epsilon = 1$
- Model as  $\sum_{j \in N} a_j x_j - (m - \epsilon)\delta \geq b + \epsilon$ 
  - $m$  is a lower bound for the expression  $\sum_{j \in N} a_j x_j - b$



## Some Last Modeling Tricks

$$\delta = 1 \Rightarrow \sum_{j \in N} a_j x_j \geq b$$

- Model as  $\sum_{j \in N} a_j x_j + m\delta \geq m + b$

$$\sum_{j \in N} a_j x_j \geq b \Rightarrow \delta = 1$$

- Model as  $\sum_{j \in N} a_j x_j - (M + \epsilon)\delta \leq b - \epsilon$
- You can obtain these by just transforming the constraints to  $\leq$  form and using the first two tricks.



## Back To Our Example...

- Use a 0-1 variable  $\delta$  to indicate whether *or not* the constraint  $2x_1 + 3x_2 \leq 1$  is satisfied.
  - $x_1, x_2$  are nonnegative continuous variables that cannot exceed 1.
- $\delta = 1 \Leftrightarrow 2x_1 + 3x_2 \leq 1$
- $M$  : Upper Bound on  $2x_1 + 3x_2 - 1$ . 4 works
- $m$  : Lower Bound on  $2x_1 + 3x_2 - 1$ . -1 works.
- $\epsilon$  : 0.1



## Example, Cont.

- ( $\Rightarrow$ ) Recall the trick.
  - $\delta = 1 \Rightarrow \sum_{j \in N} a_j x_j \leq b \Leftrightarrow \sum_{j \in N} a_j x_j + M\delta \leq M + b$
- $2x_1 + 3x_2 + 4\delta \leq 5$
- ( $\Leftarrow$ ). Recall the trick.
  - $\sum_{j \in N} a_j x_j \leq b \Rightarrow \delta = 1 \Leftrightarrow \sum_{j \in N} a_j x_j - (m - \epsilon)\delta \geq b + \epsilon$
- $2x_1 + 3x_2 + 1.1\delta \geq 1.1$

$$\begin{aligned} 2x_1 + 3x_2 + 4\delta &\leq 5 \\ 2x_1 + 3x_2 + 1.1\delta &\geq 1.1 \end{aligned}$$



## A More Realistic Example

- PPP—Production Planning Problem. (A simple linear program).
- An engineering plant can produce five types of products:  $p_1, p_2, \dots, p_5$  by using two production processes: grinding and drilling. Each product requires the following number of hours of each process, and contributes the following amount (in hundreds of dollars) to the net total profit.

	$p_1$	$p_2$	$p_3$	$p_4$	$p_5$
Grinding	12	20	0	25	15
Drilling	10	8	16	0	0
Profit	55	60	35	40	20



## PPP – More Info

- Each unit of each product take 20 manhours for final assembly.
- The factory has three grinding machines and two drilling machines.
- The factory works a six day week with two shifts of 8 hours/day. Eight workers are employed in assembly, each working one shift per day.



# PPP

maximize

$$55x_1 + 60x_2 + 35x_3 + 40x_4 + 20x_5 \quad (\text{Profit/week})$$

subject to

$$12x_1 + 20x_2 + 0x_3 + 25x_4 + 15x_5 \leq 288 \quad (\text{Grinding})$$

$$10x_1 + 8x_2 + 16x_3 + 0x_4 + 0x_5 \leq 192 \quad (\text{Drilling})$$

$$20x_1 + 20x_2 + 20x_3 + 20x_4 + 20x_5 \leq 384 \quad \text{Final Assembly}$$

$$x_i \geq 0 \quad \forall i = 1, 2, \dots, 5$$



## Another PPP Modeling Example

- Let's model the following situation.
  - If we manufacture  $P1$  or  $P2$  (or both), then at least one of  $P3$ ,  $P4$ ,  $P5$  must also be manufactured.
- We first need an indicator variable  $z_j$  that indicate when each of the  $x_j > 0$ .
  - How do we model  $x_j > 0 \Rightarrow z_j = 1$ ?
  - **Hint:** This is equivalent to  $z_j = 0 \Rightarrow x_j = 0$



## Modeling the Logic

Answer:  $x_j \leq Mz_j$

- Given that we have included the constraints  $x_j \leq Mz_j$ , we'd like to model the following implication:
  - $z_1 + z_2 \geq 1 \Rightarrow z_3 + z_4 + z_5 \geq 1$
- Can you just "see" the answer?
- I can't. So let's try our "formulaic" approach.
- Think of it in two steps
  - $z_1 + z_2 \geq 1 \Rightarrow \delta = 1$
  - $\delta = 1 \Rightarrow z_3 + z_4 + z_5 \geq 1$ .



## Look up the Tricks

- First we model the following:
  - $z_1 + z_2 \geq 1 \Rightarrow \delta = 1$
- The formula from the bag o' tricks
- $\sum_{j \in N} a_j x_j \geq b \Rightarrow \delta = 1 \Leftrightarrow \sum_{j \in N} a_j x_j - (M + \epsilon)\delta \leq b - \epsilon$
- $M$  : Upper Bound on  $\sum_{j \in N} a_j z_j - b$ 
  - $M = 1$  in this case. ( $z_1 \leq 1, z_2 \leq 1, b = 1$ ).
- $\epsilon$  : "Tolerance Level" indicating the minimum amount by which the constraint can be violated.
  - $\epsilon = 1$  in this case!
  - If the constraint is going to be violated, then it will be violated by at least one.





## Modeling $z_1 + z_2 \geq 1 \Rightarrow \delta = 1$ , Cont.

- Just plug in the formula  $\sum_{j \in N} a_j x_j - (M + \epsilon)\delta \leq b - \epsilon$ 
  - $z_1 + z_2 - 2\delta \leq 0$
- Does this do what we want?

$z_1$	$z_2$	$\delta$
0	0	$\geq 0$
0	1	$\geq 1/2(\Rightarrow = 1)$
1	0	$\geq 1/2(\Rightarrow = 1)$
1	1	$\geq 1$



## Second Part

- Want to model the following:
  - $\delta = 1 \Rightarrow z_3 + z_4 + z_5 \geq 1$ .
- The formula from the bag o' tricks
- $\delta = 1 \Rightarrow \sum_{j \in N} a_j x_j \geq b \Leftrightarrow \sum_{j \in N} a_j x_j + m\delta \geq m + b$
- $m$  : lower bound on  $\sum_{j \in N} a_j x_j - b$ .
  - $m = -1$ . ( $z_1 \geq 0, z_2 \geq 0, b = 1$ ).
- Plug in the formula:
  - $z_3 + z_4 + z_5 - \delta \geq 0$
- It works! (Check for  $\delta = 0, \delta = 1$ ).



## PPP, Make 1 or 2 $\Rightarrow$ make 3, 4, or 5

maximize

$$55x_1 + 60x_2 + 35x_3 + 40x_4 + 20x_5 \quad (\text{Profit/week})$$

subject to

$$12x_1 + 20x_2 + 0x_3 + 25x_4 + 15x_5 \leq 288$$

$$10x_1 + 8x_2 + 16x_3 + 0x_4 + 0x_5 \leq 192$$

$$20x_1 + 20x_2 + 20x_3 + 20x_4 + 20x_5 \leq 384$$

$$x_i \leq M_i z_i \quad \forall i = 1, 2, \dots, 5$$

$$z_1 + z_2 - 2\delta \leq 0$$

$$z_3 + z_4 + z_5 - \delta \geq 0$$

$$x_i \geq 0 \quad \forall i = 1, 2, \dots, 5$$

$$z_i \in \{0, 1\} \quad \forall i = 1, 2, \dots, 5$$

$$\delta \in \{0, 1\}$$



## Cool Things You Can Now Do

- Either constraint 1 or constraint 2 must hold
  - Create indicators  $\delta_1, \delta_2$ , then  $\delta_1 + \delta_2 \geq 1$
- At least one constraint of all the constraints in  $M$  should hold
  - $\sum_{i \in M} \delta_i \geq 1$
- At least  $k$  of the constraints in  $M$  must hold
  - $\sum_{i \in M} \delta_i \geq k$
- If  $x$ , then  $y$ 
  - $\delta_y \geq \delta_x$



## That’s All Folks!

- That’s it for modeling.
- You should have read N&W I.1.1 by now.
- Those of you who want to get a jump start on the homeworks can consider doing problems
  - ???
  - ???

